

L Number	Hits	Search Text	DB	Time stamp
2	22	tactic\$6 near2 agent	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:46
3	3	(aerial near2 warfare) and (tactic\$6 near2 agent)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:46
4	144	(703/17).CCLS.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:47
5	854	(703/2).CCLS.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:47
6	130	(703/20).CCLS.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:47
7	66	(706/30).CCLS.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:50
8	147	(706/60).CCLS.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:50
9	77	(706/905).CCLS.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:50
10	20	(706/913).CCLS.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:50
1	15	aerial near2 warfare	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:51
11	93	aerial near2 (warfare or combat)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:52
12	3	(tactic\$6 near2 agent) and (aerial near2 (warfare or combat))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:51
13	80	aerial near2 (combat)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:52
-	0	("6360193").PN.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/19 18:22

-	22913	aerial warfare	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2003/08/19 18:22
-	10	aerial adj warfare	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2003/08/20 12:45

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3	3	(aerial near2 warfare) and (tactic\$6 near2 agent)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:46
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12	3	(tactic\$6 near2 agent) and (aerial near2 (warfare or combat))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:51
13	80	aerial near2 (combat)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 12:52
14	2162	tactic\$6 and agent	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/20 14:12

15	2	(aerial near2 (combat)) and (tactic\$6 and agent)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2003/08/20 14:12
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[Implementing Agent Teams in Dynamic Multi-agent Environments - Tambe \(1997\) \(Correct\) \(5 citations\)](#)
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babar.inria.fr/pub/centaur/chol/paper2.ps.Z

[Proving as Editing HOL Tactics - Takahashi, Hagiya \(1999\) \(Correct\)](#)
 3: 1-000 c 1999 BCS Proving as Editing HOL **Tactics** Koichi Takahashi 1 and Masami Hagiya 2 1
 113-0033, JAPAN Keywords: Higher Order Logic **Tactic**-Based Theorem Prover User interface Emacs
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nicosia.is.s.u-tokyo.ac.jp/pub/staff/hagiya/fac99/uitp-final.ps

[Generalization and Reuse of Tactic Proofs - Amy Felty And \(Correct\) \(7 citations\)](#)
 Generalization and Reuse of **Tactic** Proofs Amy Felty and Douglas Howe AT&T Bell
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 Emergent Battlefield Behaviour through Multi-**Agent** Simulation Paul Darbyshire Hussein Abbass
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[A Tactic Language for Ergo - Martin, Nickson, Utting \(1997\) \(Correct\) \(1 citation\)](#)
 4072 Australia Technical Report No. 97-16 A **Tactic** Language For Ergo Andrew Martin, Ray Nickson, And
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prover is under development. It uses a single **tactic** language, based on Angel, for **tactic** programming, svrc.it.uq.edu.au/techreports/tr97-16.ps.gz

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 behavior flying simulated aircraft in tactical air **combat** training scenarios. The design of the system has of weapons, and communication between different **agents** in semi-natural language. The experts interpret environment at some level of representation. 3. The **agent**. The **agent** is a human or simulation model (in our
ai.eecs.umich.edu/people/laird/papers/tacair-cogsci.pdf

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Self-fulfilling Bias in Multiagent Learning - Hu, Wellman (1996) (Correct) (15 citations)
 is complicated by the fact that as other **agents** learn, the environment effectively changes. environment effectively changes. Moreover, other **agents**' actions are often not directly observable, and observable, and the actions taken by the learning **agent** can strongly bias which range of behaviors are
linux.eecs.umich.edu/.5/people/wellman/icmas96hu.ps.Z

The Common Agent - Multi-Protocol Management (Correct)
 The Common **Agent** A Multi-Protocol Management **Agent** The Common
 The Common **Agent** A Multi-Protocol Management **Agent** The Common **Agent** is an implementation of an ISO **Agent** A Multi-Protocol Management **Agent** The Common **Agent** is an implementation of an ISO compliant
www.cs.nccu.edu.tw/~jong/reports/ps/common-a.ps.gz

Trust Appraisal and Secure Routing of Mobile Agents - Swarup (1997) (Correct) (3 citations)
 Trust Appraisal and Secure Routing of Mobile **Agents** Vipin Swarup The MITRE Corporation 202 adopt a fairly general computation model of mobile **agents**. **Agent** servers are abstract processors, e.g. fairly general computation model of mobile **agents**. **Agent** servers are abstract processors, e.g.individual
www.cs.nps.navy.mil/research/languages/statements/swarup.ps

LODQ6FKPRWJHU-iQ3DUDOL --OLXVVRQWy - Tu Kosice (1998) (Correct)
 Scheduling in a Multi-**Agent** Environment
 paralic,csonto@tuke.sk Abstract. A new scheduling **agent** for existing CIM multi-**agent** system is being
 A new scheduling **agent** for existing CIM multi-**agent** system is being currently developed at the
fs-kkui2.fei.tuke.sk/papers/1998/conf/basys.ps

Geospecific rendering of alpine terrain - Premoze, Thompson, Shirley (Correct)
 paper describes an approach for using panchromatic **aerial** imagery to produce color views of alpine scenes.
www.cs.utah.edu/vissim/papers/snowTerrain/terrain.ps.gz

LAVA: Secure Delegation of Mobile Applets: Design.. - Jatin Hansoty (Correct)
 Vouk, Wu All Rights Reserved Abstract Mobile **agents** are tasks or processes which can be autonomously application areas include, for example, intelligent **agent**, network and system management, web-based mobile attractive paradigm over the Internet, this mobile **agent** technology introduces significant new security
shang.csc.ncsu.edu/papers/esw.ps.gz

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[Adaptive Agent Tracking in Real-world Multi-Agent Domains: A.. - Milind Tambe \(1997\) \(Correct\) \(1 citation\)](#)
 episodes. Our experiments in simulated air-to-air **combat** environments have shown some interesting results
 Adaptive **Agent** Tracking in Real-world Multi-**Agent** Domains: A
 Adaptive **Agent** Tracking in Real-world Multi-**Agent** Domains: A Preliminary Report Milind Tambe,
www.isi.edu/~shen/agent.ps

[Implementing Agent Teams in Dynamic Multi-agent Environments - Tambe \(1997\) \(Correct\) \(5 citations\)](#)
 above principles, one for a real-world helicopter **combat** simulation, and one for the RoboCup soccer
 Implementing **Agent** Teams in Dynamic Multi-**agent** Environments Milind
 Implementing **Agent** Teams in Dynamic Multi-**agent** Environments Milind Tambe Information Sciences
www.cs.kuleuven.ac.be/~nico/robocup/./docs/AAl.ps.gz

[A Prototype Design for Studying Emergent Battlefield.. - Through Multi-Agent.. \(Correct\)](#)
 that provides a framework for simulating a land **combat** situation using a multi-**agent** system. Emphasis is
 Emergent Battlefield Behaviour through Multi-**Agent** Simulation Paul Darbyshire Hussein Abbass
 authors. Abstract Over the past few years, Multi-**Agent** Systems have become an important tool in
www.business.vu.edu.au/infosyspapers/docs/2000/DarbyshireP2000.pdf

[Differential Games and Symbolic Programming to Calculate a.. - Ménéec \(Correct\)](#)
 Calculate a Guaranteed Aircraft Evasion in Modern **Aerial** Duels St'ephane Le M'enec Institut National de
 safety as soon as 1 Missile d'Interception de **Combat** et d'Auto-d'efense/Advanced Medium Range Air to
ftp-sop.inria.fr/secoia/lemenec/soumission-cdc94.ps.Z

[Locating Shadows in Aerial Photographs Using Imprecise.. - Mark Stevens \(1995\) \(Correct\)](#)
 Science Technical Report Locating Shadows in **Aerial** Photographs Using Imprecise Elevation Data Mark
www.cs.colostate.edu/~ftppub/TechReports/1995/tr95-105.ps.Z

[A Feasibility Study To Control Airfoil Shape Using THUNDER - Jennifer Pinkerton \(1997\) \(Correct\) \(2 citations\)](#)
 P-51 Mustang, to permit high-lift maneuvering in **aerial combat** situations (ref. 1)Until the 1970's,
 Mustang, to permit high-lift maneuvering in **aerial combat** situations (ref. 1)Until the 1970's, however,
techreports.larc.nasa.gov/pub/techreports/larc/1997/tm/NASA-97-tm4767.ps.Z

[QoS Negotiation in Real-Time Systems and Its Application .. - Abdelzaher, Atkins, Shin \(1997\) \(Correct\) \(26 citations\)](#)
 to fly an F-16 fighter aircraft modeled using the **Aerial Combat** (ACM) F-16 Flight Simulator. Experimental
 an F-16 fighter aircraft modeled using the **Aerial Combat** (ACM) F-16 Flight Simulator. Experimental results
rtcl.eecs.umich.edu/outgoing/zaher/negotiation.ps

[Daedalus Battlefield Visualization System - Edward Riseman \(1996\) \(Correct\)](#)
 The terrain map will be produced from **aerial** images by the UMass terrain reconstruction system
 timely situation awareness for air and ground **combat** operations in order to improve force
vis-ftp.cs.umass.edu/Papers/riseman/iuw96_Daedalus.ps.gz

[GPS, Aerial triangulation, Block adjustment, Ground control accuracy - Ra Cy \(Correct\)](#)
 Gps Supported **Aerial** Triangulation Using Untargeted Ground Control
wwwphoto.eng.ohio-state.edu/isprs3/sympo98.man/pp02.ps

[Moose Aerial Observation Manual - Nest Technical Manual \(Correct\)](#)
 Moose **Aerial** Observation Manual NEST Technical Manual TM-008

www.borealscience.on.ca/pdfs/netm008.pdf

A Digital Airborne Camera System for Photogrammetry and.. - Helmut Heier Alexander (1999) (Correct)
camera system. 1. INTRODUCTION For many decades **Aerial** Cameras developed and manufactured by Carl Zeiss
www.ipi.uni-hannover.de/htm-deutsch/publikationen/1999/isprs-workshop/cd/pdf-papers/heier.pdf

Non-Linear Adaptive Auto-Pilot for Uninhabited Aerial.. - Maruthi Akella Center (Correct)
Non-Linear Adaptive Auto-Pilot for Uninhabited **Aerial Combat** Vehicles. Maruthi R, Akella Center for Adaptive Auto-Pilot for Uninhabited **Aerial Combat** Vehicles. Maruthi R, Akella Center for System
aero.tamu.edu/~kamesh/Papers/AIAA_99_Portland.pdf

AFV-II: Robotic Aerial Platform for Autonomous Robot Research - Anthony Lewis (Correct)
AFV-II: Robotic **Aerial** Platform for Autonomous Robot Research M.
usc.edu/pub/nn_robotics/papers/autonomous.robots/94/afv2.ps.Z

A Java Application Framework for Agent Based Systems - Kendall, Krishna, Pathak.. (2000) (Correct)
(1 citation)
A Java Application Framework for **Agent** Based Systems Elizabeth.A.Kendall, P.V.Murali
AUSTRALIA email :kendall@rmit.edu.au Abstract **Agents** are the next significant software abstraction, abstraction, especially for distributed systems. **Agent** based systems have been developed in response to
www.cse.rmit.edu.au/~rdsek/papers/frame.ps

A Sanctuary for Mobile Agents - Yee (1997) (Correct) (31 citations)
A Sanctuary for Mobile **Agents** Bennet S. Yee February 18, 1997 1 Introduction
is building a secure infrastructure for mobile **agents**, and examining the fundamental security limits of of computation. With standard approaches for **agent**-based systems, a malicious server has access to
www.cs.virginia.edu/~survive/DOCS/MA_sanctuary.ps

WORDS: Automatic tie point extraction, Aerial triangulation, Block .. - Ig Ht (Correct)
lii/1 Key Words: Automatic Tie Point Extraction, **Aerial** Triangulation, Block Adjustment, Quality,
wwwphoto.eng.ohio-state.edu/isprs3/sympo98.man/pp08.ps

Microsoft TerraServer^TM - Tom Barclay Robert (Correct)
and Development John Hoffman, Natt Robb III, **Aerial** Images Hedy Rossmeissl, Beth Duff, George Lee,
research.microsoft.com/~gray/Papers/MSR_TR_98_17_TerraServer.pdf

Pitfalls of Agent-Oriented Development - Wooldridge, Jennings (1998) (Correct) (27 citations)
Pitfalls of **Agent**-Oriented Development Michael Wooldridge and
the theoretical and experimental foundations of **agent**-based systems are becoming increasingly well devoted to understanding the pragmatics of (multi-**agent** systems development -the everyday reality of
www.csee.umbc.edu/~nicholas/courses/691d/papers/paod.ps

On Entering an Open Society - Costa, Hübner, Bordini (1994) (Correct)
Abstract This paper concerns the problem of **agent** migration between open societies. In particular, In particular, it focuses on the problems of an **agent** entering an open society. Two functional levels [DEM 90]In particular, it deals with open multi-**agent** systems, here called open societies. The problem
www.cs.ucl.ac.uk/staff/ucacrhb/Publications/EnteringOpenSoc.ps.gz

Modelling Competitive Co-operation of Agents in a.. - Brazier, van Eck, Treur (1997) (Correct) (1 citation)
Modelling Competitive Co-operation of **Agents** in a Compositional Multi-**Agent** Framework Frances Co-operation of **Agents** in a Compositional Multi-**Agent** Framework Frances Brazier, Pascal van Eck and 1 Introduction In many multi-**agent** domains competitive **agents** need to co-operate. In
www.cs.vu.nl/~wai/Papers/EKAW97.exacc.ps

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